

ELECTRICAL ENGINEERING

PAPER-I

1. Circuits—Theory:

- Circuit components; network graphs; KCL, KVL;
- Circuit analysis methods: nodal analysis, mesh analysis; basic network theorems and applications; transient analysis: RL, RC and RLC circuits; sinusoidal steady state analysis; resonant circuits; coupled circuits; balanced 3-phase circuits. Two-port networks.

2. Signals and Systems:

- Representation of continuous-time and discrete-time signals and systems; LTI systems; convolution; impulse response; time-domain analysis of LTI systems based on convolution and differential/difference equations.
- Fourier transform, Laplace transform, Z-transform, Transfer function.
- Sampling and recovery of signals DFT, FFT Processing of analog signals through discrete-time systems.

3. E.M. Theory:

- Maxwell's equations, wave propagation in bounded media. Boundary conditions, reflection and refraction of plane waves.
- Transmission lines: travelling and standing waves, impedance matching, Smith chart.

4. Analog Electronics:

- Characteristics and equivalent circuits (large and small-signal) of Diode, BJT, JFET and MOSFET.
- Diode circuits: Clipping, clamping, rectifier. Biasing and bias stability. FET amplifiers. Current mirror;
- Amplifiers: single and multi-stage, differential, operational feedback and power. Analysis of amplifiers; frequency-response of amplifiers. OPAMP circuits. Filters;
- Sinusoidal oscillators: criterion for oscillation;
- single-transistor and OPAMP configurations.
- Function generators and wave-shaping circuits. Linear and switching power supplies.

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5. Digital Electronics:

- Boolean algebra; minimisation of Boolean functions; logic gates; digital IC families (DTL, TTL, ECL, MOS, CMOS).
- Combinational circuits: arithmetic circuits, code converters, multiplexers and decoders. Sequential circuits: latches and flipflops, counters and shift-registers.
- Comparators, timers, multivibrators. Sample and hold circuits, ADCs and DACs.
- Semiconductor memories.
- Logic implementation using programmable devices (ROM, PLA, FPGA).

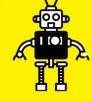
6. Energy Conversion:

- Principles of electromechanical energy conversion : Torque and emf in rotating machines.
- DC machines: characteristics and performance analysis; starting and speed control of motors.
- Transformers: principles of operation and analysis; regulation, efficiency; 3-phase transformers. 3-phase induction machines and synchronous machines: characteristics and performance analysis; speed control.

7. Power Electronics and Electric Drives:

 Semi-conductor power devices: diode, transistor, thyristor, triac, GTO and MOSFET-static characteristics and principles of operation; triggering circuits; phase control rectifiers; bridge converters: fullycontrolled and half-controlled; principles of thyristor choppers and inverters; DC-DC converters; Switch mode inverter; basic concepts of speed control of dc and ac motor drives applications of variablespeed drives.

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8. Analog Communication:

- Random variables: continuous, discrete; probability, probability functions. Statistical averages; probability models;
- Random signals and noise: white noise, noise equivalent bandwidth; signal transmission with noise; signal to noise ratio.
- Linear CW modulation : Amplitude modulation : DSB, DSB-SC and SSB. Modulators and Demodulators;
- Phase and Frequency modulation: PM & FM signals; narrows band FM; generation & detection of FM and PM, Deemphasis, Preemphasis.
- CW modulation system: Superhetrodyne receivers, AM receivers, communication receivers, FM receivers, phase locked loop, SSB receiver Signal to noise ratio calculation or AM and FM receivers.

PAPER II

1. Control Systems:

- Elements of control systems; block-diagram representations; openloop & closed-loop systems; principles and applications of feedback. Control system components.
- LTI systems: time-domain and transform-domain analysis.
- Stability: Routh Hurwitz criterion, root-loci, Bode-plots and polor plots, Nyquist's criterion; Design of lead-lad compensators.
 Proportional, PI, PID controllers. State-variable representation and analysis of control systems.
- 2. **Microprocessors and Microcomputers**: PC organisation; CPU, instruction set, register settiming diagram, programming, interrupts, memory interfacing, I/O interfacing, programmable peripheral devices.









3. Measurement and Instrumentation:

- Error analysis; measurement of current voltage, power, energy, power-factor, resistance, inductance, capacitance and frequency; bridge measurements.
- Signal conditioning circuit; Electronic measuring instruments: multimeter, CRO, digital voltmeter, frequency counter, Q-meter, spectrum-analyser, distoration-meter.
- Transducers: thermocouple, thermistor, LVDT, strain-guage, piezoelectric crystal.

4. Power Systems:

- Analysis and Control: Steady-state performance of overhead transmission lines and cables; principles of active and reactive power transfer and distribution; per-unit quantities; bus admittance and impedance matrices; load flow; voltage control and power factor correction; economic operation; symmetrical components, analysis of symmetrical and unsymmetrical faults.
- Concepts of system stability: swing curves and equal area criterion.
 Static VAR system. Basic concepts of HVDC transmission.

5. **Power System Protection:**

- Principles of overcurrent, differential and distance protection.
 Concept of solid state relays. Circuit brakers.
- Computer aided protection: introduction; line, bus, generator, transformer protection; numeric relays and application of DSP to protection.

6. Digital Communication:

- Pulse code modulation (PCM), defferential pulse code modulation (DPCM), delta modulation (DM), Digital modulation and demodulation schemes: amplitude, phase and frequency keying schemes (ASK, PSK, FSK).
- Error control coding: error detection and correction, linear block codes, convolation codes. Information measure and source coding. Data networks, 7-layer architecture.

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